XCT25L4_Y汽车起重机 / Truck Crane

技术规格书 Technical specifications













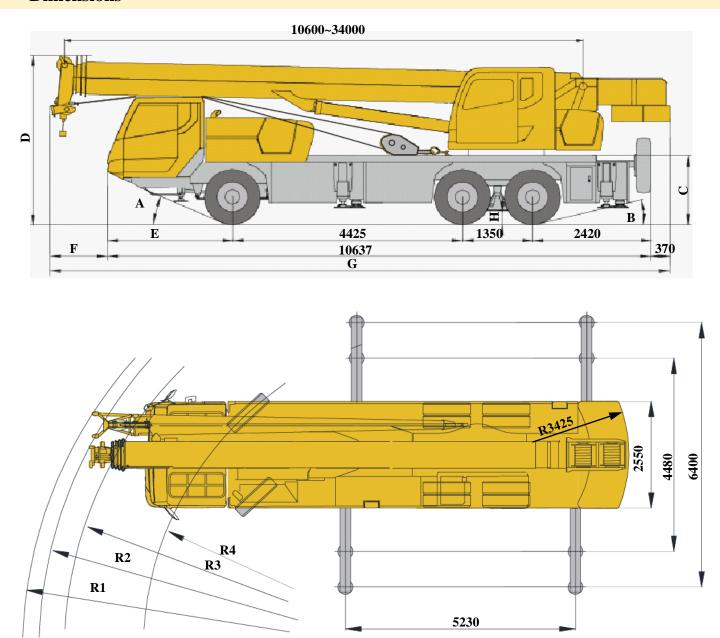
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尺寸参数(右驾 Right-hand drive)

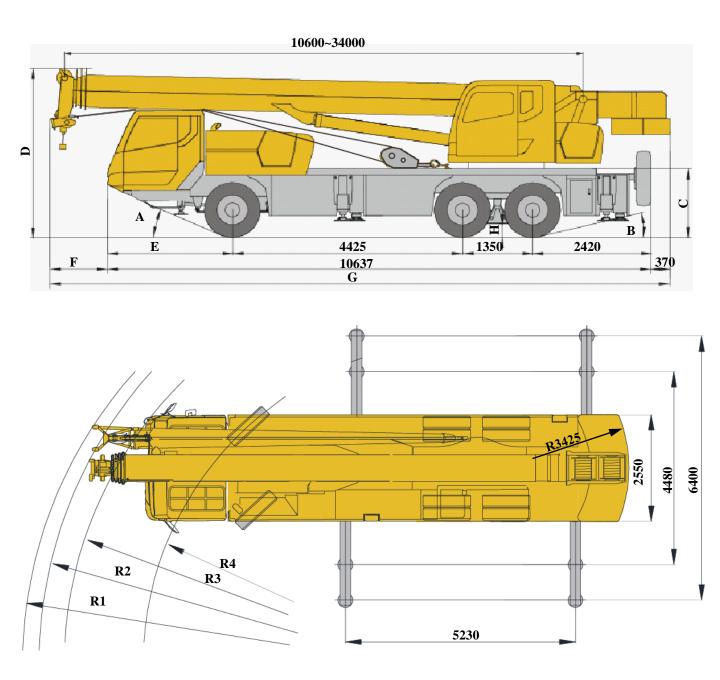
Dimensions



副臂型式 Jib		A	В	с	D	E	F	G	R1	R2	R3	R4	н
侧置副臂 Swing- away jib	11.00-20	16.5	13°	1392	3420	2442	1528	12535	12500	12250	11500	10000	261
腹置副臂 Under slung jib	11.00-20	16.5	13°	1392	3920	2442	1935	12942		12500	11500	10000	261

尺寸参数 (左驾 Left-hand drive)

Dimensions



	A	В	С	D	E	F	G	R1	R2	R3	R4	н
11.00-20	16.5°	13°	1392	3420	2442	1528	12535	12500	12250	12000	10000	261

Technical specifications

车架 支腿	徐工设计、制造,全覆盖式走台板,防扭转箱型结构,高强度钢材制造。 4支腿,H形布置,操作杆控制液压动作。可由底盘任一侧同时或单独控制各支腿的动作,设有水平仪。 支腿油缸均设有单向阀,且垂直支腿带有双向液压锁。配第五支腿。 纵向×横向(全伸)5.23m×6.40m	配置 ●		前悬架采用少片变截面钢板弹簧,自重轻,噪音低,舒适性好;后悬架采用橡胶悬架,V型推力杆,自重轻,定位效果好,免维护,维修方便。前悬架采用少片变截面钢板弹簧,自重轻,噪音低,舒适性好;后悬架采用钢板弹簧平衡梁加V型推力杆结构,钢板弹簧和平衡梁总成作为承载部件同时还兼做导向部件和V型推力杆共同对车桥进行定位,对车桥定位效果比	右机 左机
	支脚盘尺寸φ400mm 第五支腿支脚盘尺 寸φ260mm 最大起重量时支腿反力: 326kN		制动	较好,能够防止中后桥错位。 双回路、气压制动、鼓式制动器。 行车制动:双回路气压制动,作用于 所有车轮。	
发动机	SC7H260Q3,直列六缸增压、中冷 柴油发动机,上柴制造,额定功率 192kW/2200rpm,最大扭矩 1000Nm/1400rpm,国三排放标准。 燃油箱容积:240L。 SC7H260Q5,直列六缸增压、中冷 柴油发动机,上柴制造,额定功率 192kW/2300rpm,最大扭矩 1000Nm/1200~1600rpm,国五排放	● 右机 ● 左机型	转向 驾驶室	驻车制动:放气制动,作用于2-3轴车轮。 辅助制动:发动机排气制动,安全可靠,延长制动摩擦片使用寿命。 机械式转向机构,带有液压助力。 新型全头钢结构驾驶室,采用四点式连接结构,两侧外开式车门。主驾可手动调节高度;副驾采用双座椅,可展开为简易卧铺,便于驾驶员临时	•
变速箱 车桥	标准。燃油箱容积:240L。 陕齿机械全同步器变速箱,8个前进挡,两个倒档。 3桥底盘,美驰单级减速桥。	•		休息。 安全玻璃配备电动升降器 , 隔热效果良好 ; 后视镜可电动调节 , 安全方便 ; 方向盘可调节高度及角度 适合各个高度的操作人群。	•
	3桥底盘,选用汉德单级减速桥,性 能可靠	右驾 机型 ● 左驾		配备冷暖空调。 直流24伏特,串联12伏特的蓄电池2 个。发电机输出电压 28±0.3V,输 出电流70A	•
轮胎	11.00-20,适用于重型载重车辆,通 用性强 轮胎规格:11.00R20	机型 ●○	置	液压双向锁 ABS 黄色反光标识	● ○ ○ 右驾机型

Technical specifications

	上车	配置
结构	徐工设计、制造,高强度钢材制造	•
液压系统	定量泵+负载敏感多路阀系统;多路阀采用分合流技术,起升、变幅伸缩单独动作时可以双泵合流,主副卷作业速度高达135m/min,主、副卷与伸缩、变幅复合动作时双泵独立供油。	•
操纵方式	机械操纵。	● 机械 机型
	先导液比例操纵,由左右2个操纵 手柄控制。无级调速。	● 先导 机型
主副起升 机构	液压控制调速,装有双折线绳槽卷筒,由液压马达通过行星齿轮减速器驱动,内置常闭式制动器并带有平衡阀。 具有轻载高速、重载低速的特点。	•
回转机构	单排球外齿式回转支承,右侧布置单回转机构,由液压马达驱动行星齿轮回转机构减速器驱动,可连续回转360°。具有动力控制或自由滑转的功能,可无级调速。	•
变幅机构	单变幅油缸,带有自补偿功能的平 衡阀	•
操纵室	按人机工程学设计,外开式车门,可调式座椅。 装有安全玻璃和顶部保护栏。前窗 装有遮阳板。 配备单冷空调。	•
	操纵杆加长节	へ 机械 机型
平衡重	固定式平衡重4.2t。	•

安全装置	液压平衡阀;	
	液压溢流阀;	
	力矩限制器;	
	操纵杆弹簧式回中系统;	
	三圈保护器,防止钢丝绳过放;	
	臂头设置高度限位,防止钢丝绳过	
	卷;	
	自由滑转,回转锁止,三色警示灯	
	角度指示器	0
	卷扬监视装置	0
	三色报警灯	0
	回转警示灯	0
	黄色反光标识	0
		右驾 机型
吊钩	25t吊钩,	
	3t吊钩	•
	20t吊钩	0

Technical specifications

SINKS.	臂架系统	配置
主臂	伸缩臂采用抗扭曲设计,采用高 强度结构钢制造,四节U形截面主 臂,采用单缸绳排伸缩方式。	•
	主臂长度:10.6m~34m	
臂端单滑		•
轮侧黑刺麻	绳起重作业,起重性能与主臂相同,但最大起重量不超过2.8t。	
侧直副臂	由连接架、旋转架和桁架结构折 叠式副臂组成,具有0°、15°、30° 三种安装角,收存在主臂旁。 固定副臂长度:8.3m。	•
腹置副臂	采用箱型腹置副臂,安装角度5°、 15°、30°。 固定副臂长度:8.3m。	○ 右驾 机型

产品各部件明细如上所述,具体部件细请参 照产品报价单 符号说明:

- —— 表示标准配置;○ —— 表示选装配置。

技术规格 Technical specifications

J.J.	Zhassis	
Frame	Designed and manufactured by XCMG, it is made of high strength steel with fully covered walking surface and anti-torsion box-typed structure.	•
Outrigger s	Four outriggers arranged in H-shape are hydraulically controlled by control levers. There is an outrigger control station located at each side of the chassis, and there is a level gauge on each control station. The outrigger movements can be simultaneously or separately controlled at any side of the chassis. There is a check valve fitted in each outrigger cylinder, and a double-way hydraulic valve fitted in each jack cylinder. Fifth jack is equipped. Longitudinal × lateral (fully-extended): 5.23 m×6.40 m Outrigger float diameter: φ400 mm 5th jack float diameter: φ260 mm Reaction force of outrigger at max. lifting load: 326 kN	•
Engine	SC7H260Q3, in-line, 6-cylinder, supercharged, intercooled diesel engine, made by Shanghai Diesel Engine, with rated power of 192 kW/2200 rpm, max. torque of 1000 Nm/1400 rpm, compliant with China III emission standard. Fuel tank capacity: 240 L.	Right- hand drive
	SC7H260Q5, in-line, 6-cylinder, supercharged, intercooled diesel engine, made by Shanghai Diesel Engine, with rated power of 192kW/2300rpm, max. torque of 1000Nm/1200 ~ 1600rpm, compliant with China V emission standard. Fuel tank capacity: 240 L.	Left- hand drive
Transmissi on	Mechanical transmission with a synchronizer, made by Shaanxi Fast Gear Co., Ltd., 8-forward speed and 2-reverse speed.	•
Alxes	Three-axle chassis, Meritor single-stage reduction axle 3-axle chassis with HANDE single	Right- hand drive
	reduction axle., with reliable performance.	Left- hand drive
Tires	11.00-20, suitable for heave load vehicles, strong commonality.	•
	Tire specifications: 11.00 R20	0

Suspensions	Leaf springs with tapered cross-section are adopted for front suspensions, light dead weight and low noise; rubber spring suspensions with V-type push rods are adopted for rear axles, light dead weight and free of maintenance.	Right- hand drive
	Less leaf springs with tapered cross- section are adopted for front suspension, light dead weight, low noise and great comfort; the rear suspension adopts leaf springs and balance beam with V-type push rods. The leaf spring and balance beam assembly are the bearing parts as well as the guiding parts, which are used to position the axles together with V-type push rods and thus the misalignment of the middle and rear axles can be avoided.	Left- hand drive
Brakes	Double-circuit, air pressure brake, drum brake. Service brake: double-circuit air pressure brake acting on all wheels. Parking brake: air-release brake, acting on wheels of axles 2-3. Auxiliary brake: engine exhaust brake, which is safe and reliable, and will prolong the service life of brake lining.	•
Steering	Mechanically steering mechanism with a hydraulic booster	•
Driver's cab	New type, steel, full dimension cab with 4-point connecting structure, has swing-out doors at both sides. Manually adjustable driver's seat in height is available. A simple sleeper for the co-driver's seat is installed to supply comfort and reduce fatigue. The cab has better thermal insulation effect. Safety glass, electrically operated door window lifters, electrically adjusted mirrors make operation convenient and safe. Steering wheel is adjustable in height and angle. Heater and Air conditioner is standard.	•
Electrical system	24 V DC, two sets of 12 V battery in series. Generator output voltage is 28±0.3 V, and output current is 70 A.	•
Safety	Double-way hydraulic valve	•
devices	ABS	0
	Yellow reflecting marking.	O Right- hand drive

技术规格 Technical specifications

	Superstructure	
Frame	Designed and manufactured by XCMG, made of high strength steel.	•
Hydraulic system	Constant displacement pump + load-sensing multi-way valve; with confluence technology adopted for multi-way valve, double-pump confluence can be realized when lifting, elevating or telescoping operation is carried out independently. Max. hoisting speed of main and auxiliary winches is up to 135 m/min. For simultaneous movements of main/auxiliary winch, telescoping or elevating, the two pumps supply oil separately.	•
Operating mode	Mechanical control	Mechani
	Pilot hydraulic proportional control through left and right levers is used for controlling the superstructure. Stepless speed regulation is available.	eal Pilot
	Hydraulic control is used for speed regulation. The system is driven by a hydraulic motor through a planetary gear reducer, with a normally closed brake, balance valve and a grooved drum equipped. It has features of high speed with a light load and low speed with a heavy load.	•
Slewing system	Single-row, contact-ball, external tooth slewing ring, with a single slewing gear located at right side, is driven by the planetary gear reducer of slewing mechanism, which is driven by a hydraulic motor, and may continuously slew 360°. Power control or free slewing function is available, and the slewing speed may be infinitely regulated.	•
Elevating system	Single cylinder with self-compensation balanced valve.	•
Operator' s cab	Ergonomically designed, with swing- out door and adjustable seat. It is equipped with safe glass and roof protective grille. Windshield is equipped with sun visor. Air conditioning is standard.	•
	Extension of control lever	O Mechani cal

counterwei ght	Fixed counterweight of 4.2 t.	•
Safety	Hydraulic balance valve;	
devices	Hydraulic relief valve; Load moment limiter; Spring centering system for control levers; Lowering limiter for preventing wire rope from over releasing; Anti-two block at boom head for preventing wire rope from overwinding; Free sliding, slewing locking and tri	•
	colored light bar. Angle indicator	0
	winch monitoring device	0
	tri colored light bar	0
	beacon lamp	0
	Yellow reflecting marking.	O Right- hand drive
Hook block	25 t hook block , 3 t hook block	•
	20 t hook block	0

Technical specifications

SINKS.	Boom and jib system	
Boom	Four-section boom with U-shape profile, made of high strength steel, with special anti-deformation design. Single cylinder plus ropes is used to telescope the boom. Boom length: 10.6 m ~ 34 m	•
Single top	Fitted at boom head, used for single line operation. Its lifting performance is the same as that for boom, but the maximum lifting load does not exceed 2.8 t.	•
Swing-away jib	The jib consists of a connecting bracket, a rotating bracket and a foldable lattice jib. Three offset angles of 0°, 15° and 30° are available. It is stowed along the side of the boom. Fixed jib length: 8.3 m.	•
Under lung jib	Box-type under lung jib, with offset angles of 5°, 15° and 30°. Fixed jib length: 8.3 m.	O Right- hand drive

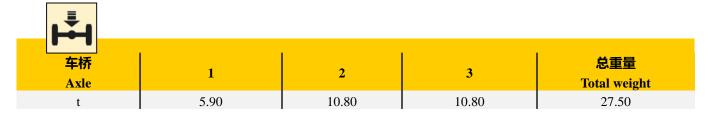
Product parts list is as mentioned above. Please refer to the product quotation for specific parts.

Symbol explanation:

- —it means the standard configuration;—it means the optional configuration.

重量

Weight



	The state of the s							
吊钩 倍率		吊钩重量	吊钩尺寸	备注				
	Hook	Parts of line	Weight (kg)	Dimensions (mm)	Remarks			
	25t	10	297	1175×450×417	单钩 Single hook , 标配 Standard			
	20t	7	200	1249×430×268	单钩 Single hook , 选配 Optional			
	3t	1	60	518×236×236	单钩 Single hook , 标配 Standard			

作业速度 Working speeds

*(*A)



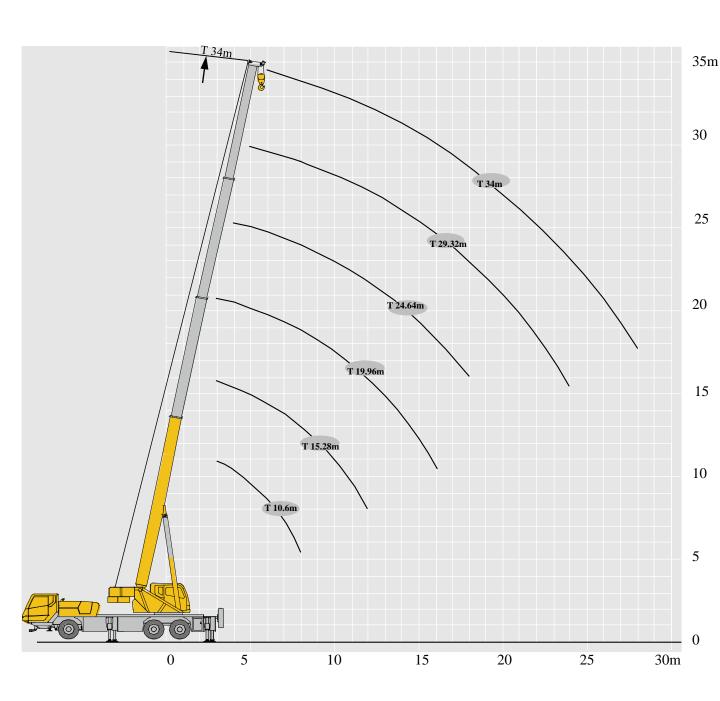
作业机构 Drive	作业速度 Working speed	最大单绳拉力 Max. single line pull	钢丝绳直径/长度 Rope diameter/ length		
	m/min , 单绳 , 第四层 m/min, single line, 4th layer	30 kN	14 mm/170 m		
[2]	m/min , 单绳 , 第四层 0-135 m/min, single line, 4th layer	30 kN	14 mm/110 m		
360.	0-3 r/min				
	从0°抬起至80°约35s Approx. 35 s for boom elevation from 0° to 80°				
1/7	从10.6m伸出至34m约53s Approx. 53s for boom extension from 10.6	m to 34 m			

臂架组合方案

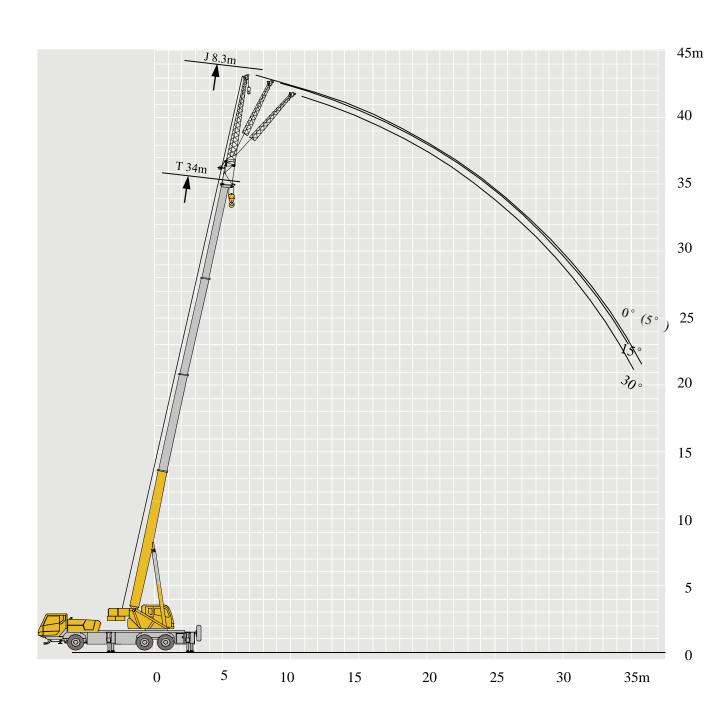
Boom / Jib combinations



主臂	副臂
Telescopic boom	Jib
T: 10.6~34.0m	T: 34.0m J: 8.3 m



	10.6-34m 6.4m	×5.23m 360°					
	10.6m	15.28m	19.96m	24.64m	29.32m	34m	
3	25	16					3
3.5	23	16	16				3.5
4	22.5	16	16	13.5			4
4.5	21.7	16	16	13			4.5
5	19.7	16	16	12.8	10.5		5
5.5	17.7	16	15.2	12.5	10.5		5.5
6	15.9	15.5	14.3	11.8	10.5	6.9	6
7	12.1	12.6	12.8	10.8	10	6.9	7
8	9.9	10.4	10.6	9.8	9.2	6.9	8
9		8.5	8.7	8.8	8.4	6.7	9
10		7.1	7.3	7.4	7.5	6.3	10
12		5.2	5.3	5.4	5.5	5.3	12
14			4.1	4.2	4.2	4.3	14
16			3.2	3.3	3.3	3.4	16
18				2.6	2.7	2.75	18
20				2.1	2.1	2.2	20
22				1.6	1.7	1.8	22
24					1.4	1.45	24
26					1.1	1.2	26
28						0.9	28
30						0.7	30



起重性能表 Lifting capacities

T 34m

R	8.3m 6.4m×5.23m 360°			
	0°(侧置副臂)(Swing-away jib) 5°(腹置副臂)(Under slung jib)	15°	30°	
79	2.8	2	1.6	79
78	2.8	2	1.6	78
76	2.8	1.85	1.5	76
74	2.7	1.8	1.45	74
72	2.6	1.75	1.4	72
70	2.45	1.6	1.35	70
68	2.35	1.55	1.3	68
66	2.2	1.45	1.25	66
64	2.05	1.35	1.2	64
62	1.9	1.25	1.15	62
60	1.75	1.15	1.1	60
58	1.65	1.05	1.05	58
56	1.5	1	1	56
54	1.25	0.95	0.95	54
52	1.1	0.9	0.9	52
50	1	0.85	0.75	50
45	0.75	0.55	0.55	45
40	0.55	0.45	0.45	40
35	0.4	0.3	0.3	35
30	0.25			30

注意事项

Notes

- 1. 表中额定总起重量值,是在平整的坚固地面上本起重机能够保证的最大总起重量,包括吊钩和吊具的重量,所以为了估算重物重量,必须减去上述的装置重量。
- 表中的工作幅度为起吊重物离地时起重物到起 重机回转轴线的水平距离,是包括起重臂变形 量在内的实际值,因而起吊前应考虑起重臂变 形量。
- 只允许在5级(瞬时风速14.1m/s,风压 125N/m2)风以下进行作业。
- 4. 吊重前操作者必须对物体的重量和工作范围了解后选择合适的作业工况,严禁超出表中的数值。幅度及臂长在相邻两个数值之间时,应依据两个数值中较小值确定起重作业。
- 5. 应按主臂仰角范围作业,即使是空载,也不应 使主臂仰角处于范围外,谨防整机倾翻。
- 表中的主臂长度应要按照每节臂的伸缩要求进行伸出。

- The total rated loads given in the rated load charts are the maximum lifting capacity when the crane is set up on firm and level ground, which includes the weight of the hook block and slings. The weight of above-mentioned devices should be deducted from the rated lifting load.
- 2. The working radius shown in the rated load charts is the radius when the load is lifted off the ground, and it is the actual value including loaded boom deflection. Take boom deflection into consideration before beginning a lifting operation.
- 3. A lifting operation is permissible only when the wind force is below grade 5 (instantaneous wind speed is 14.1 m/s, wind pressure is 125 N/m2).
- 4. Before beginning lifting operation, the operator should know the weight of the load to be lifted and its working range, and then select proper working conditions. Never operate the crane beyond the limit shown in the chart. Use the lower value from the chart when the boom length or working radius is between the range of values.
- 5. Observe the boom angle limit. Never operate the crane with the boom angle beyond the recommended limit even if a load is not being carried. Otherwise, the crane will tip.
- The boom should be extended according to the telescoping code shown by percentage (or digits, which means the percentage of boom sections extended).

符号标识

Description of symbols

常规标识 General symbols							
	上车 Superstructure		- F	底盘 Chassis			
t	起重能力 Lifting capacity		H÷H	车桥 Axle			
1//	吊臂长度 Boom length		km/h	行驶速度 Driving speed			
	工作幅度 Radius		F	爬坡能力 Grade ability			
	吊臂仰角 Boom angle			轮胎 Tires			
	主臂起升高度 Hoist height with boom			支腿 Outriggers			
	固定副臂长度 Fixed jib length		t	吊钩 Hook block			
	副臂安装角 Jib offset angle			平衡重 Counterweight			
	副臂起升高度 Hoist height with jib			卷扬 Winch			
	不使用第五支腿侧后方作业 Boom over side or over rear of the crane without 5th jack		360°	360°全回转 360° operation of the boom			
360°	使用第五支腿360°全回转 360° operation of the boom with 5th						

jack down

主要技术参数表

Table of main technical parameters

米미	佐口	⇔ /⊹	参数Parameter			
类别 Category	项目 Item	单位 Unit	右驾	左驾		
Category	Item	Cint	Right-hand drive	Left-hand drive		
			12535×2550×3420			
	外形尺寸(长×宽×高)	mm	(侧置副臂Swing-away jib)	12535×2550×3420		
	Dimensions (lengthxwidthxheight)		12942×2550×3920			
	## DE 2234		(腹置副臂Under lung jib)			
尺寸参数	轴距 Wheel base	mm	4425+1350	4425+1350		
Dimensio	轮距(前/后) Track (Front/ Rear)	mm	2055/1834	2027/1834		
ns	前悬/后悬 Front/ Rear overhang	mm	2442/2420	2442/2420		
			1528/370			
	前伸/后伸	mm	(侧置副臂Swing-away jib)	1528/370		
	Front/ Rear extension	111111	1935/370	1320/370		
	最大允许总质量最大允许总质量		(腹置副臂Under lung jib)			
重量参数·	Total vehicle mass in travel configuration	kg	27500	27500		
里里多数 Weight	轴荷 —轴 1st axle	kg	5900	5900		
Weight	Axle 二轴 2nd axle	kg	10800	10800		
	load 三轴 3rd axle	kg	10800	10800		
	发动机型 号 Engine model		SC7H260Q3	SC7H260Q5		
动力参数	额定功率/转速 Engine rated power/rpm	kW/(r/min)	192/2200	192/2300		
Power	最大净功率/转速 Max. net power/rpm	kW/(r/min)	188/2200	188/2300		
	最大输出扭矩/转速 Max. output torque/rpm	N.m/(r/min)	1000/1400	1000/1200 ~ 1600		
	最高车速 Max. travel speed	km/h	≥85	≥85		
	最低稳定车速	1 0	2 2	2 2		
	Min. stable travel speed	km/h	2~3	2~3		
	最小转弯直径	m	≤20	≤20		
	Min. turning diameter					
	肖太敏小特号且任 Min. turning diameter at boom tip	m	≤25	≤25		
	最小离地间隙	mm	261	261		
行驶参数	Min. ground clearance	111111	201	201		
Travel	接近角 Approach angle	0	16.5	16.5		
		0	13	13		
-	Departure angle 制动距离(制动初速度为30km/h)					
	向対距离(南対が速度が30km/h) Braking distance (at 30 km/h)	m	≤10	≤10		
	最大爬坡能力	%	≥42	≥42		
	Max. grade ability	/0	<u>_</u> T2	_72		
	百公里油耗 Fuel consumption per 100 km	L	30	30		
	加速行驶机外噪声					
噪音	Exterior noise level	dB(A)	≤84	≤84		
Noise	驾驶员耳旁噪声	ID (1)	400	40.0		
	Noise level at seated position	dB(A)	≤90	≤90		
	r					

主要技术参数表

Table of main technical parameters

<u> 기</u> 수 □ 대	120			** 1.2	参数Parameter		
类别 Category	项目 Item		单位 Unit	右驾	左驾		
					Right-hand drive	Left-hand drive	
	最大额定总起重量 Max. total rated lifting capacity			t	25	25	
	最小额定工作幅度 Min. rated working radius			m	3	3	
	转台尾部回转半经 Turning radius at turntable tail			mm	3425	3425	
		基本臂 Base boom		kN.m	965	965	
	最大起重力矩 Max. load moment	最长主臂 Fully-extended boom		kN.m	623	623	
		最长主臂+副臂 Fully-extended boom + Jib		kN.m	370	370	
	支腿跨距	纵向	Longitudinal	m	5.23	5.23	
主要性能参数	Outrigger span	横向] Lateral	m	6.4	6.4	
Main			基本臂 se boom	m	10.9	10.9	
performance	起升高度 Hoist height	最长主臂 Fully-extended boom		m	34.5	34.5	
		最长主臂+副臂 Fully-extended boom + Jib		m	43.2	43.2	
		基本臂 Base boom		m	10.6	10.6	
	起重臂长度	最长主臂 Fully-extended boom		m	34	34	
	Boom length	最长主臂+副臂 Fully-extended boom + Jib		m	42.3	42.3	
	副臂安装角 Jib offset angle			0	0, 15, 30 (侧置副臂 Swing-away jib) 5, 15, 30 (腹置副臂 Under slung jib)	0, 15, 30	
	起重臂起臂时间 Boom raising time			s	≤35	≤35	
	起重臂全伸时间 Boom fully extending time			S	≤53	≤53	
	最大回转速度 Max. slewing speed			r/min	≥3	≥3	
		水平支腿	收 Retracting	S	≤20	≤20	
工作速度参数 Working	支腿收放时间	Outrigger beam	放 Extending	S	≤25	≤25	
speed	Outrigger extending and retracting time	垂直支腿	收 Retracting	S	≤20	≤20	
		Outrigger -	放 Extending	S	≤25	≤25	
	起升速度(单绳,第四 层,空载) Hoisting speed (single	主起升机构 Main winch		m/min	≥135	≥135	
	line, 4th layer, no 副起升机构		【构 Auxiliary winch	m/min	≥135	≥135	
噪声	机外辐射 Exterior noise level			dB (A)	≤120	≤120	
Noise	司机位置处 Noise level at seated position			dB (A)	≤90	≤90	



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